Static analysis of avionics software for security TLS-SEC

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Airbus Avionics Software

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Avionics Software Security properties Static analysis Operational semantics Denotationa •00

- - Finite traces semantics

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Airbus Cockpit Avionics Software

Software functions	
Aircraft Control Domain (C, asm)	
 flight control systems 	DAL A
flight warning systems	DAL B or DAL C
communication systems	DAL C
Airline Information Services Domain (Java)	
 administrative functions 	DAL E
 maintenance support 	DAL E

Software platforms	
ATSU LynxOS [®] -based <i>POSIX</i> Host Platform	×86, DAL C
IMA ARINC 653 Integrated Modular Avionics	PowerPC, DAL A
$ASF\xspace$ PikeOS $^{\textcircled{R}}\xspace$ -based Avionics Server Function	PowerPC, DAL C

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Safety standards

Critical avionics software is subject to certification:

- regulated by international standards (DO-178 rev. B/C)
- verification = more than half of the development cost
- mostly based on massive test campaigns & intellectual reviews

Current trend:

use of formal methods now acknowledged (DO-178C, DO-333)

- at the binary level, to replace testing
- at the source level, to replace intellectual reviews
- at the source level, to replace testing

provided the correspondence with the binary is also certified

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Denotational semantics









 Avionics Software
 Security properties
 Static analysis
 Operational semantics
 Denotational

Security concerns for aircraft embedded systems

Aircraft functions increasingly performed by software-intensive systems

Airline flight ops & cabin facilities \rightarrow connectivity

- to external untrusted networks
- O to avionics maintenance & ground-board communication

Enhanced control automation, HMI comfort, systems interoperability, configurability

- → exponential complexity increase (SW, HW, networks)
- → harder to ensure freedom from security vulnerabilities



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Major trends in avionics

Imore and more generic avionics platforms

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growing parts developed by third parties

Security risks for aircraft embedded systems Major trends in avionics

More and more generic avionics platforms

- → standard HW & communication protocols
- → Commercial-Off-The-Shelf components
- ightarrow likely to be known to unspecialised attackers

Growing parts developed by third parties

- ightarrow less grip on processes
- ightarrow need for automated security assurance



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Airbus assets to be protected against threats

- aircraft operational safety
- aircraft operational & dispatch reliability
- commercial branding & image (Airbus & Airline)



Increasing security-related regulatory constraints

Federal Register: April 13, 2007

http://www.gpo.gov/fdsys/pkg/FR-2007-04-13/html/E7-7065.htm

FAA emitted special conditions for **B787** certification bc

"The architecture of the Boeing Model 787-8 computer systems and networks may allow access to external systems and networks, such as wireless

airline operations and maintenance systems, satellite communications, electronic mail, the internet, etc. Onboard wired and wireless devices may also

have access to parts of the airplane's digital systems that provide flight critical functions." "These new connectivity capabilities may result in security

vulnerabilities to the airplane's critical systems."

January 2010: similar special conditions for B747-8

http://www.gpo.gov/fdsys/pkg/FR-2010-01-15/html/2010-661.htm

December 2013: similar special conditions for Airbus A350

https://federalregister.gov/a/2013-29985

December 2013: EASA requested all airborne systems with datalink capabilities to be re-assessed for potential security vulnerabilities related to the processing of misformatted messages.



Pending standards for avionics

• RTCA Special Committee 216 (SC-216) to

"help ensure safe, secure and efficient operations amid the growing use of highly integrated electronic systems and network technologies used

on-board aircraft, for CNS/ATM systems and air carrier operations and maintenance."

- RTCA SC-216 / EUROCAE WG-72 collaboration
 - Minimum Aviation System Performance Standards (MASPS) for Aeronautical Electronic and Networked Systems Security
 - Security Assurance and Assessment Processes and Methods for Safety-related Aircraft Systems
 - Security process specification
 - ED-203 Airworthiness Security Methodology and Instructions
- State-of-the-art techniques should be proposed



Categories of security properties

Integrity

assets modified only by authorised parties in authorised ways

threats: buffer overflow attacks, spoofing

protections: access control, digital signatures, replication



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assets read only by authorised parties

threats: leakage of sensitive secret information

protections: ciphering, partitioning, information flow control



Categories of security properties

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Confidentiality

assets read only by authorised parties

threats: leakage of sensitive secret information

protections: ciphering, partitioning, information flow control

Availability

assets are accessible to authorised parties in a timely manner

threats: denial of service attacks

Research directions

Integrity

buffer overflow analyses (synchronous and asynchronous)

information flow analyses (trusted vs tainted)

formal proof of security functionalities

Confidentiality

information flow analyses (public vs secret) formal verification of cryptographic protocols quantitative assessment of crypto primitives (also integrity)
(also integrity)
(also integrity)

Availability

WCET and termination analyses

resource consumption analyses



Main short-term objective: memory safety Minimal integrity property

Goal: no run-time error!

no buffer overflow, invalid pointer arithmetic or dereference no overflows in float, integer, enum arithmetic and cast

no division, modulo by 0 on integers and floats



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Means of assurance

certified avionics \Rightarrow soundness required

internal software \Rightarrow **C** source code available

intellectual reviews costly and error-prone \Rightarrow automation necessary

⇒ Solution: sound static analysis



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 Security properties
 Static analysis
 Operational semantics
 Denotational

Example: Sendmail buffer overflow

email address parsing Discovered 2003 by Mark Dowd

```
#define BUFFERSTZE 200
#define TRUE 1
#define FALSE 0
int copy it ( char * input , unsigned int length ) {
    char c . localbuf [ BUFFERSIZE ];
    unsigned int upperlimit, quotation, roundquote, inputIndex, outputIndex:
    upperlimit = BUFFERSIZE - 10;
    guotation = roundguote = FALSE ;
    inputIndex = outputIndex = 0;
    while ( inputIndex < length ) {</pre>
        c = input [ inputIndex ++];
        if (( c == '<') && (! guotation )) {
            quotation = TRUE ; upperlimit --;
        if (( c == '>') && ( guotation )) {
            quotation = FALSE ; upperlimit ++;
        if (( c == '(') && (! guotation ) && ! roundguote ) {
            roundquote = TRUE : //upperlimit--: // decrementation was missing
in bua
        if (( c == ')') && (! guotation ) && roundguote ) {
            roundquote = FALSE : upperlimit ++:
        // If there is sufficient space in the buffer , write the character .
        if ( outputIndex < upperlimit ) {</pre>
            localbuf [ outputIndex ] = c:
            outputIndex ++;
    if ( roundquote )
        localbuf [ outputIndex ] = ')'; outputIndex ++; }
    if ( quotation )
        localbuf [ outputIndex ] = '>'; outputIndex ++; }
```

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return 0;

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Static analysis

- Abstract interpretation
- Example of abstract interpreta

- Run-time error analysis



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Sound static analysis

Characteristics:

- direct analysis of the source code (not a model)
- automatic (easy to set up, no interaction with the user)
- efficient
- approximate (to sidestep decidability and efficiency issues)

Soundness:

- semantic-based (C specification, machine integers, floats, pointers, ...)
- full coverage of all control and data
- any property found by analysis holds on every program execution \implies no error missed, no false negative
- soundness is required by DO

Abstract interpretation: theory of the approximation of semantics derive sound analysis with controllable cost/precision trade-off

Agenda

Static analysis

Abstract interpretation

- Example of abstract interpretation
- False alarms
- Abstraction refinement
- Abstract domains
- Run-time error analysis

Operational semantics

- Definitions
- a. E1, 10, 11



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Principle of abstract interpretation

Define the concrete semantics of your system or program

 $\begin{array}{l} \mbox{concrete semantics} \equiv \mbox{mathematical model of the set} \\ \mbox{of all its possible behaviours in all possible environments} \\ \mbox{can be constructed from semantics of commands} \\ \mbox{of system specification or programming language} \end{array}$



Principle of abstract interpretation

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Define a specification

specification \equiv subset of possible behaviours



Principle of abstract interpretation

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Define a specification

specification \equiv subset of possible behaviours

Conduct a formal proof

that the concrete semantics meets the specification

use computers to automate the proof



Concrete semantics of system/program *F*



Semantics[|P|]

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Specification of P (e.g. safety property)



Specification[|P|]



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 Security properties
 Static analysis
 Operational semantics
 Denotational

Formal proof of P



 $Semantics[|P|] \subseteq Specification[|P|]$

Excluded miracle

Undecidability

The concrete semantics of a system/program is not computable.

⇒ Most questions on system/program behaviour are undecidable.



Excluded miracle

Undecidability

The concrete semantics of a system/program is not computable.

> Most questions on system/program behaviour are undecidable.

Example: termination is undecidable

- assume termination(P) always terminates and returns true iff P always terminates on all input data
- the following program yields a contradiction

P := while termination(P)do ()done

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Test/simulation



Subset of the possible behaviours \Rightarrow incomplete

Abstract semantics for P



Abstraction(Semantics[|P|])



Proof by abstract interpretation



 $Abstraction(Semantics[|P|]) \subseteq Specification[|P|]$



Soundness of abstract interpretation



 $Semantics[|P|] \subseteq Abstraction(Semantics[|P|]) \subseteq Specification[|P|]$



Formal methods are abstract interpretations

static analysis abstract semantics computed automatically ≜ predefined abstractions may be tailored by the user


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5

Concrete semantics: set of (discrete) traces





Collecting semantics

Collect the set of states that can appear on some trace at any given discrete time :





Trace abstraction : collecting abstraction

This an abstraction. Does the red trace exist? Trace semantics: $no \neq collecting semantics: | don't know.$





Set abstraction : intervals





Set abstraction : intervals





From set of traces to set of reachable states



set of (discrete) traces

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From set of traces to set of reachable states



traces of sets of states



From set of traces to set of reachable states



trace of sets of states

From set of traces to set of reachable states



trace of intervals

From set of traces to set of reachable states



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Effective computation : intialisation

From set of traces to set of reachable states



Effective computation : propagation

From set of traces to set of reachable states



From set of traces to set of reachable states



Effective computation : widening unstable constraints

From set of traces to set of reachable states



Effective computation : stability of interval constraints

Interval analysis

Program to be analyzed

x := 1; 1: while x < 10000 do 2: x := x + 1 3: od; 4:



Equations (abstract interpretation of the semantics)

```
X_1 = [1, 1]
                     X_2 = (X_1 \cup X_3) \cap [-\infty, 9999]
  x := 1;
                     1:
  while x < 10000 do
2:
      x := x + 1
3:
  od;
4:
```



Interval analysis

Resolution by increasing iterations

$$\begin{array}{l} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{cases} X_1 = [1, 1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1, 1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \end{cases} \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \end{cases} \\ \begin{array}{l} 2: \\ x := x + 1 \\ 3: \\ \text{od}; \\ 4: \end{array} \end{cases} \begin{cases} X_1 = \emptyset \\ X_2 = \emptyset \\ X_3 = \emptyset \\ X_4 = \emptyset \end{cases} \end{cases}$$



Interval analysis

Resolution by increasing iterations

$$\begin{array}{l} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{vmatrix} X_1 = [1, 1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1, 1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \end{vmatrix}$$

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Interval analysis

Resolution by increasing iterations

$$\begin{array}{c} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{cases} X_1 = [1, 1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1, 1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \\ 2: \\ x := x + 1 \\ 3: \\ \text{od}; \\ 4: \end{cases} \begin{cases} X_1 = [1, 1] \\ X_2 = [1, 2] \\ X_3 = [2, 3] \\ X_4 = \emptyset \end{cases}$$

Interval analysis

Resolution by increasing iterations

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Resolution by increasing iterations

x := 1; 1: while x < 10000 do	$egin{aligned} X_1 &= [1,1] \ X_2 &= (X_1 \cup X_3) \cap [-\infty,9999] \ X_3 &= X_2 \oplus [1,1] \ X_4 &= (X_1 \cup X_3) \cap [10000,+\infty] \end{aligned}$
2: x := x + 1 3: od;	$egin{aligned} X_1 &= [1,1] \ X_2 &= [1,3] \ X_3 &= [2,4] \ X_4 &= \emptyset \end{aligned}$



Resolution by increasing iterations

 $egin{aligned} X_1 &= & [1,1] \ X_2 &= & (X_1 \cup X_3) \cap [-\infty,9999] \end{aligned}$ x := 1: 1: while x < 10000 do 2: $|X_1 = [1, 1]$ x := x + 1 $X_2 = [1,4]$ 3: $\begin{vmatrix} x_2 \\ X_3 \\ X_4 \\ X_4 \\ = \emptyset \end{vmatrix}$ od: 4:



Interval analysis

Resolution by increasing iterations

$$\begin{array}{l} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{cases} X_1 = [1, 1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1, 1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \end{cases} \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \end{cases} \\ 2: \\ x := x + 1 \\ 3: \\ \text{od}; \\ 4: \end{cases} \begin{cases} X_1 = [1, 1] \\ X_2 = [1, 4] \\ X_3 = [2, 5] \\ X_4 = \emptyset \end{cases} \end{cases}$$

Interval analysis

Resolution by increasing iterations

$$\begin{array}{l} x := 1; \\ 1: \\ while x < 10000 \ do \end{array} \begin{vmatrix} X_1 = [1, 1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1, 1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \end{vmatrix}$$

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Interval analysis

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Convergence speed-up by widening

$$\begin{array}{ll} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{vmatrix} X_1 = [1, 1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1, 1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \end{vmatrix}$$

$$\begin{array}{ll} 2: \\ x := x + 1 \\ 3: \\ \text{od}; \\ 4: \\ \end{vmatrix} \begin{vmatrix} X_1 = [1, 1] \\ X_2 = [1, +\infty] \\ X_3 = [2, 6] \\ X_4 = \emptyset \end{vmatrix} \iff \text{widening}$$

Decreasing iterations

$$\begin{array}{l} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{cases} X_1 = [1, 1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1, 1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \\ X_5 = [1, 1] \\ X_2 = [1, +\infty] \\ X_3 = [2, +\infty] \\ X_4 = \emptyset \end{array}$$



Decreasing iterations

$$\begin{array}{l} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{cases} X_1 = [1,1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty,9999] \\ X_3 = X_2 \oplus [1,1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \\ 2: \\ x := x + 1 \\ 3: \\ \text{od}; \\ 4: \end{cases} \begin{cases} X_1 = [1,1] \\ X_2 = [1,9999] \\ X_3 = [2, +\infty] \\ X_4 = \emptyset \end{cases}$$



Decreasing iterations

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Final solution

$$\begin{array}{l} x := 1; \\ 1: \\ \text{while } x < 10000 \text{ do} \end{array} \begin{pmatrix} X_1 = [1,1] \\ X_2 = (X_1 \cup X_3) \cap [-\infty, 9999] \\ X_3 = X_2 \oplus [1,1] \\ X_4 = (X_1 \cup X_3) \cap [10000, +\infty] \\ 2: \\ x := x + 1 \\ 3: \\ \text{od}; \\ 4: \end{array} \begin{pmatrix} X_1 = [1,1] \\ X_2 = [1,9999] \\ X_3 = [2,+10000] \\ X_4 = [+10000,+10000] \\ \end{array}$$



Result of interval analysis

<pre>x := 1; 1: {x = 1} while x < 10000 do</pre>	$egin{aligned} X_1 &= [1,1] \ X_2 &= (X_1 \cup X_3) \cap [-\infty,9999] \ X_3 &= X_2 \oplus [1,1] \ X_4 &= (X_1 \cup X_3) \cap [10000,+\infty) \end{aligned}$
2: { $x \in [1, 9999]$ }	$[X_1 - [1 \ 1]]$
x := x + 1 3: $\{x \in [2, +10000]\}$	$egin{array}{c} X_1 &= [1,1] \ X_2 &= [1,9999] \ X_3 &= [2,+10000] \end{array}$
od; 4: $\{x = 10000\}$	$X_4 = [+10000, +10000]$

Formal proof of absence of overflow

x := 1;1: {x = 1} while x < 10000 do 2: {x \le [1,9999]} x := x + 1 3: {x \le [2, +10000]} od; 4: {x = 10000}


10. IS. IS.

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Agenda



Static analysis

- Abstract interpretation
- Example of abstract interpretation

False alarms

- Abstraction refinement
- Abstract domains
- Run-time error analysis

Operational semantics

- Definitions



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Alarms





True error





Incompleteness \Rightarrow false alarms





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False alarms (e.g. interval analysis)



\Rightarrow need for abstraction refinement

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Set of functions



How to approximate $\{f_1, f_2, f_3, f_4\}$?

Abstraction of set of functions



A less precise abstraction

f(t) t

Concrete questions on the f



Concrete questions answered in the abstract



Min/max questions on the f_i

Soundness of the abstraction



No concrete case is ever forgotten.



A more precise/refined abstraction



A even more precise/refined abstraction



Passing to the limit



Sound and *complete* abstraction for min/max questions on the f_i



A non-comparable abstraction



Sound and <u>in</u>complete abstraction for min/max questions on the f_i



The hierarchy of abstractions





10. IS. IS.

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False alarms (e.g. interval analysis)



\Rightarrow need for abstraction refinement

Examples of numerical abstract domains



Combinations of abstractions



(In)finite sets of (in)finite traces

Combinations of abstractions



Set of points (x_i, y_i) , Hoare logic



Combinations of abstractions

Sign abstraction



 $x \ge 0$, $y \ge 0$



Combinations of abstractions



 $a \leq x \leq b, \ c \leq y \leq d$



Combinations of abstractions

Octagon abstraction



 $\pm x \pm y \leq b$



Combinations of abstractions

Polyhedral abstraction



 $a \cdot x + b \cdot y \leq c$



Combinations of abstractions



 $(x-a)^2+(y-b)^2\leq c$



Combinations of abstractions

Exponential abstraction



 $a^x \leq y$



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- Abstraction refinement
- Abstract domains
- Run-time error analysis



- Definitions



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194

Static analysis of synchronous **C** programs Concrete semantics and specification

Concrete semantics source

- C99 standard (portable C programs)
- IEEE 754-1985 standard (floating-point arithmetic)
- architecture parameters (sizeof, endianess, struct, etc.)
- compiler and linker parameters (initialization, etc.)



Static analysis of synchronous **C** programs Concrete semantics and specification

Concrete semantics source

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- architecture parameters (sizeof, endianess, struct, etc.)
- compiler and linker parameters (initialization, etc.)

Run-time errors

- overflows in float, integer, enum arithmetic and cast
- division, modulo by 0 on integers and floats
- invalid pointer arithmetic or dereferencing
- violation of user-specified assertions

Some of ASTRÉE's numerical abstract domains



relational domains are necessary to infer precise bounds

(C) A. Miné

The ASTRÉE static analyser

<u>Analyseur</u> \underline{S} tatique A static analyzer for **C** programs

- developed by CNRS/ENS (from 2002) and AbsInt GmbH
- commercialised by AbsInt since 2010



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Characteristics

sound and automatic, scales up to very large programs

- ② specialised for control-command programs \Rightarrow few false alarms
- parametric \Rightarrow fine-tuning by end-users



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Deployment at Airbus

from 2012 A380/A400M/A350 fly-by-wire control software (DAL A) successful proofs of absence of *run-time error* ≃ 6 hours for 700,000 lines of **C** from 2016 all new software products (on-going effort)

Back to Sendmail buffer overflow

email address parsing true alarms detected

```
#define BUFFERSTZE 200
#define TRUE 1
#define FALSE 0
int copy it ( char * input , unsigned int length ) {
    char c . localbuf [ BUFFERSIZE ];
    unsigned int upperlimit, quotation, roundquote, inputIndex, outputIndex:
    upperlimit = BUFFERSIZE - 10;
    guotation = roundguote = FALSE ;
    inputIndex = outputIndex = 0;
    while ( inputIndex < length ) {</pre>
        c = input [ inputIndex ++];
        if (( c == '<') && (! guotation )) {
            quotation = TRUE ; upperlimit --;
        if (( c == '>') && ( guotation )) {
            quotation = FALSE ; upperlimit ++;
        if (( c == '(') && (! guotation ) && ! roundguote ) {
            roundquote = TRUE : //upperlimit--: // decrementation was missing
in bua
        if (( c == ')') && (! guotation ) && roundguote ) {
            roundquote = FALSE : upperlimit ++:
        // If there is sufficient space in the buffer , write the character .
        if ( outputIndex < upperlimit ) {</pre>
            localbuf [ outputIndex ] = c:
            outputIndex ++;
    if ( roundquote )
        localbuf [ outputIndex ] = ')'; outputIndex ++; }
    if ( quotation )
        localbuf [ outputIndex ] = '>'; outputIndex ++; }
```



return 0;
Back to Sendmail buffer overflow

email address parsing but false alarms still

```
#define BUFFFRSTZE 200
#define TRUE 1
#define FALSE 0
int copy it ( char * input , unsigned int length ) {
    char c . localbuf [ BUFFERSIZE ];
    unsigned int upperlimit, quotation, roundquote, inputIndex, outputIndex:
    upperlimit = BUFFERSIZE - 10;
    guotation = roundguote = FALSE ;
    inputIndex = outputIndex = 0;
    while ( inputIndex < length ) {</pre>
        c = input [ inputIndex ++];
        if (( c == '<') && (! guotation )) {
            quotation = TRUE ; upperlimit --;
        if (( c == '>') && ( guotation )) {
            quotation = FALSE ; upperlimit ++;
        if (( c == '(') && (! guotation ) && ! roundguote ) {
            roundquote = TRUE ; upperlimit--; // decrementation was missing in
bua
        if (( c == ')') && (! guotation ) && roundguote ) {
            roundquote = FALSE : upperlimit ++:
        // If there is sufficient space in the buffer , write the character .
        if ( outputIndex < upperlimit ) {</pre>
            localbuf [ outputIndex ] = c:
            outputIndex ++;
    if ( roundquote )
        localbuf [ outputIndex ] = ')'; outputIndex ++; }
    if ( quotation )
        localbuf [ outputIndex ] = '>'; outputIndex ++; }
```

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return 0;

Back to Sendmail buffer overflow fixed and tuned

email address parsing zero alarm

```
#define BUFFERSTZE 200
#define TRUE 1
#define FALSE 0
int copy it ( char * input , unsigned int length ) {
    char c . localbuf [ BUFFFRSTZF ]:
    unsigned int upperlimit, quotation, roundquote, inputIndex, outputIndex:
 ASTREE boolean pack((upperlimit, inputIndex, outputIndex; guotation,
roundquote));
    upperlimit = BUFFERSIZE - 10;
    quotation = roundquote = FALSE :
    inputIndex = outputIndex = 0;
    while ( inputIndex < length ) {</pre>
        c = input [ inputIndex ++];
        if (( c == '<') && (! guotation )) {
            guotation = TRUE ; upperlimit --;
        if (( c == '>') && ( guotation )) {
            quotation = FALSE ; upperlimit ++;
        if (( c == '(') && (! guotation ) && ! roundguote ) {
            roundquote = TRUE : upperlimit--: // decrementation was missing in
        if (( c == ')') && (! guotation ) && roundguote ) {
            roundquote = FALSE : upperlimit ++:
        // If there is sufficient space in the buffer . write the character .
        if ( outputIndex < upperlimit ) {</pre>
            localbuf [ outputIndex ] = c;
            outputIndex ++;
 ASTREE_assert((outputIndex <= BUFFERSIZE-10));</pre>
    if ( roundquote ) {
        localbuf [ outputIndex ] = ')': outputIndex ++: }
    if ( quotation ) {
```

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Static analysis of parallel **C** programs Concrete semantics and specification

Model: real-time operating system

- fixed set of concurrent threads on a single processor
- shared memory
- synchronisation primitives
- real-time scheduling with fixed priorities
 - e.g. A380/A400M/A350 IMA, A350 ASF, SA/LR ATSU
- mono-threaded startup \neq multi-threaded run

(implicit communications)

(fixed set of mutexes)

(restriction)

(priority-based)

Static analysis of parallel **C** programs Concrete semantics and specification

- Model: real-time operating system
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(restriction)

(priority-based)

(implicit communications)

(fixed set of mutexes)

Run-time errors

- classic C run-time errors
- (overflows, invalid pointers, etc.)
- unprotected data-races

- (report & factor in the analysis)
- incorrect system calls, deadlocks
- but NOT livelocks, priority inversions

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The ASTRÉEA prototype static analyser

An extension of ASTRÉE

- <u>Analyseur Statique de logiciels Temps-RÉ</u>el <u>Embarqués</u> <u>Asynchrones</u>
- developed by CNRS/ENS/INRIA since 2009

13/10/2015 1st official merge with AbsInt's commercial ASTRÉE



The ASTRÉEA prototype static analyser

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- <u>A</u>nalyseur <u>S</u>tatique de logiciels <u>T</u>emps-<u>RÉ</u>el <u>E</u>mbarqués <u>A</u>synchrones
- developed by CNRS/ENS/INRIA since 2009

13/10/2015 1st official merge with AbsInt's commercial ASTRÉE

results with Airbus				
static analysis of A380 FWS				
 15 processes 				
$\simeq~$ 2 million lines of C				
 nested loops, complex data structures 				
\simeq 900 alarms				



Schéma producteur(s)-consommateur(s)

producteur

```
produire ressource v

lock(m);

while (i + 1 \equiv_N j) do wait(c, m);

b[i] \leftarrow v;

i \leftarrow i \oplus_N 1;

signal(c');

unlock(m)
```

consommateur

```
lock(m);

while (i = j) do wait(c', m);

w \leftarrow b[j];

j \leftarrow j \oplus_N 1;

unlock(m);

signal(c);

consommer ressource w
```



Schéma producteur(s)-consommateur(s)

producteur

produire ressource v lock(m); while $(i + 1 \equiv_N j)$ do wait(c, m); $b[i] \leftarrow v$; $i \leftarrow i \oplus_N 1$; signal(c'); unlock(m)

<u>consommateur</u>

lock(*m*); **while** (*i* = *j*) **do wait**(*c'*, *m*); $w \leftarrow b[j];$ $j \leftarrow j \oplus_N 1;$ **unlock**(*m*); **signal**(*c*); WARN: mutex unlocked *consommer ressource w*

WARNS: data-races (dans le modèle)



Avionics Software Security properties Static analysis Operational semantics Denotational semantics conditional semantics conditional semantics operational semantics conditional semantics conditional

Schéma producteur(s)-consommateur(s)

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```
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```
lock(m);

while (i = j) do wait(c', m);

w \leftarrow b[j];

j \leftarrow j \oplus_N 1;

signal(c);

unlock(m);

consommer ressource w
```



Schéma producteur(s)-consommateur(s)

producteur

produire ressource v lock(m); while $(i + 1 \equiv_N j)$ do wait(c, m); $b[i] \leftarrow v$; WARN: array out of bounds $i \leftarrow i+1$; WARN: integer overflow signal(c'); unlock(m)

consommateur

```
lock(m);

while (i = j) do wait(c', m);

w \leftarrow b[j];

j \leftarrow j \oplus_N 1;

signal(c);

unlock(m);

consommer ressource w
```



Schéma producteur(s)-consommateur(s)

erratum : verrou non pris

producteur

produire ressource v lock(m); while $(i + 1 \equiv_N j)$ do wait(c, m);

 $b[i] \leftarrow v;$ $i \leftarrow i \oplus_N 1;$ signal(c'); unlock(m)

<u>consommateur</u>

lock(*m*); while (i = j) do wait(c', m); WARN: mutex not owned $w \leftarrow b[j];$ $j \leftarrow j \oplus_N 1;$ signal(c); WARN: mutex unlocked unlock(m);consommer ressource w

WARNS: data-races



Schéma producteur(s)-consommateur(s)

erratum : mauvais mutex

producteur

produire ressource v lock(m); while $(i + 1 \equiv_N j)$ do wait(c, m); $b[i] \leftarrow v$; $i \leftarrow i \oplus_N 1$; signal(c'); WARN: mutex unlocked unlock(m)

consommateur

lock(m'); **while** (i = j) **do wait**(c', m'); $w \leftarrow b[j]$; $j \leftarrow j \oplus_N 1$; **signal**(c); WARN: mutex unlocked **unlock**(m'); *consommer ressource w*

WARNS: data-races



Operational semantics Denotationa

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4 Operational semantics

Transition systems and small step

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- Summary



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Operational semantics

Operational semantics

Mathematical description of the execution of programs

a model of programs: transition systems

- definition, a small step semantics
- example: a simple imperative language
- Itrace semantics: a families of big step semantics
 - finite and infinite executions
 - fixpoint-based definitions



Agenda

Operational semantics

• Transition systems and small step semantics

Traces semantics

- Oefinitions
- Finite traces semantics
- Fixpoint definition

• Summary





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Definition

We will characterize a program by:

- states: photography of the program status at an instant of the execution
- execution steps: how do we move from one state to the next one

Definition: transition systems (TS)

A transition system is a tuple $(\mathbb{S}, \rightarrow)$ where:

- $\bullet~\mathbb{S}$ is the set of states of the system
- $\rightarrow \subseteq \mathcal{P}(\mathbb{S} \times \mathbb{S})$ is the transition relation of the system

Note:

• the set of states may be infinite



A simple imperative language: syntax

We now look at a more classical **imperative language** (intuitively, a bare-bone subset of C):

- variables \mathbb{X} : finite, predefined set of variables
- \bullet labels $\mathbb{L}:$ before and after each statement

• values
$$\mathbb{V}: \mathbb{V}_{int} \cup \mathbb{V}_{float} \cup \ldots$$

Syntax

AIKBUS

A simple imperative language: states

A **non-error state** should fully describe the configuration at one instant of the program execution:

• the memory state defines the current contents of the memory

 $m \in \mathbb{M} = \mathbb{X} \longrightarrow \mathbb{V}$

- the control state defines where the program currently is
 - analoguous to the program counter
 - can be defined by adding labels $\mathbb{L}=\{\mathit{l}_0,\mathit{l}_1,\ldots\}$ between each pair of consecutive statements; then:

 $\mathbb{S} = \mathbb{L} \times \mathbb{M} \uplus \{\Omega\}$



A simple imperative language: semantics of expressions

- The semantics [[e]] of expression e should evaluate each expression into a value, given a memory state
- Evaluation errors may occur: division by zero... error value is also noted $\boldsymbol{\Omega}$
- Thus: $\llbracket \mathbf{e} \rrbracket : \mathbb{M} \longrightarrow \mathbb{V} \uplus \{\Omega\}$

Definition, by induction over the syntax:

$$\begin{bmatrix} v \end{bmatrix}(m) &= v \\ \begin{bmatrix} x \end{bmatrix}(m) &= m(x) \\ \llbracket e_0 + e_1 \rrbracket(m) &= \llbracket e_0 \rrbracket(m) \pm \llbracket e_1 \rrbracket(m) \\ \llbracket e_0 / e_1 \rrbracket(m) &= \begin{cases} \Omega & \text{if } \llbracket e_1 \rrbracket(m) = 0 \\ \llbracket e_0 \rrbracket(m) / / \llbracket e_1 \rrbracket(m) & \text{otherwise} \end{cases}$$

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where $\underline{\oplus}$ is the machine implementation of operator \oplus , and is Ω -strict, i.e., $\forall v \in \mathbb{V}, v \underline{\oplus} \Omega = \Omega \underline{\oplus} v = \Omega.$

A simple imperative language: semantics of conditions

- The semantics [[c]] of condition c should return a boolean value
- It follows a similar definition to that of the semantics of expressions: $[\![c]\!]:\mathbb{M}\longrightarrow \mathbb{V}_{\mathrm{bool}} \uplus \{\Omega\}$

Definition, by induction over the syntax:

$$\begin{bmatrix} \text{TRUE} \end{bmatrix}(m) &= \text{TRUE} \\ \begin{bmatrix} \text{FALSE} \end{bmatrix}(m) &= \text{FALSE} \\ \end{bmatrix} \begin{bmatrix} e_0 < e_1 \end{bmatrix}(m) &= \begin{cases} \text{TRUE} & \text{if } \llbracket e_0 \rrbracket(m) < \llbracket e_1 \rrbracket(m) \\ \text{FALSE} & \text{if } \llbracket e_0 \rrbracket(m) \ge \llbracket e_1 \rrbracket(m) \\ \Omega & \text{if } \llbracket e_0 \rrbracket(m) = \Omega \text{ or } \llbracket e_1 \rrbracket(m) = \Omega \\ \end{bmatrix} \begin{bmatrix} e_0 = e_1 \rrbracket(m) &= \begin{cases} \text{TRUE} & \text{if } \llbracket e_0 \rrbracket(m) = \llbracket e_1 \rrbracket(m) \\ \text{FALSE} & \text{if } \llbracket e_0 \rrbracket(m) = \llbracket e_1 \rrbracket(m) \\ \Omega & \text{if } \llbracket e_0 \rrbracket(m) = \Omega \text{ or } \llbracket e_1 \rrbracket(m) \\ \end{bmatrix} \end{bmatrix} \begin{bmatrix} e_0 = e_1 \rrbracket(m) &= \begin{cases} \text{FALSE} & \text{if } \llbracket e_0 \rrbracket(m) = \llbracket e_1 \rrbracket(m) \\ \Omega & \text{if } \llbracket e_0 \rrbracket(m) = \Omega \text{ or } \llbracket e_1 \rrbracket(m) = \Omega \end{bmatrix} \end{bmatrix}$$

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A simple imperative language: transitions

We now consider the transition induced by each statement.

Case of assignment $l_0 : x = e; l_1$

- if $\llbracket e \rrbracket(m) \neq \Omega$, then $(\ell_0, m) \rightarrow (\ell_1, m[x \leftarrow \llbracket e \rrbracket(m)])$
- if $\llbracket e \rrbracket(m) = \Omega$, then $(l_0, m) \to \Omega$

Case of condition l_0 : if(c){ l_1 : b_t l_2 } else{ l_3 : b_f l_4 } l_5

• if
$$\llbracket c \rrbracket(m) = \text{TRUE}$$
, then $(l_0, m) \rightarrow (l_1, m)$
• if $\llbracket c \rrbracket(m) = \text{FALSE}$, then $(l_0, m) \rightarrow (l_3, m)$
• if $\llbracket c \rrbracket(m) = \Omega$, then $(l_0, m) \rightarrow \Omega$
• $(l_2, m) \rightarrow (l_5, m)$
• $(l_4, m) \rightarrow (l_5, m)$



A simple imperative language: transitions

Case of loop
$$l_0$$
: while(c){ l_1 : b_t l_2 } l_3
• if $[c](m) = \text{TRUE}$, then $\begin{cases} (l_0, m) \rightarrow (l_1, m) \\ (l_2, m) \rightarrow (l_1, m) \end{cases}$
• if $[c](m) = \text{FALSE}$, then $\begin{cases} (l_0, m) \rightarrow (l_3, m) \\ (l_2, m) \rightarrow (l_3, m) \end{cases}$
• if $[c](m) = \Omega$, then $\begin{cases} (l_0, m) \rightarrow \Omega \\ (l_2, m) \rightarrow \Omega \end{cases}$

Case of $\{l_0 : i_0; l_1 : ...; l_{n-1}i_{n-1}; l_n\}$

• the transition relation is defined by the individual instructions



Extending the language with non-determinism

The language we have considered so far is a bit limited:

- it is deterministic: at most one transition possible from any state
- it does not support the input of values

Changes if we model non deterministic inputs...

... with an input instruction:

- i ::= ... | x := input()
- $l_0 : x := input(); l_1$ generates transitions

$$\forall v \in \mathbb{V}, \ (l_0, m) \rightarrow (l_1, m[x \leftarrow v])$$

• one instruction induces non determinism



Semantics of real world programming languages

C language:

- several norms: ANSI C'99, ANSI C'11, K&R...
- o not fully specified:
 - undefined behavior
 - **implementation dependent behavior**: architecture (ABI) or implementation (compiler...)
 - unspecified parts: leave room for implementation of compilers and optimizations
- formalizations in HOL (C'99), in Coq (CompCert C compiler)

OCaml language:

- more formal...
- ... but still with some unspecified parts, e.g., execution order

Operational semantics Denotationa

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4 Operational semantics

Transition systems and small step

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Traces semantics

- Summary



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Execution traces

- So far, we considered only states and atomic transitions
- We now consider program **executions** as a whole

Definition: traces

- A finite trace is a finite sequence of states s_0, \ldots, s_n , noted $\langle s_0, \ldots, s_n \rangle$
- An infinite trace is an infinite sequence of states $\langle s_0, \ldots \rangle$

Besides, we write:

- \mathbb{S}^* for the set of finite traces
- S^ω for the set of infinite traces
- $\mathbb{S}^{\infty} = \mathbb{S}^{\star} \cup \mathbb{S}^{\omega}$ for the set of finite or infinite traces



Semantics of finite traces

We consider a transition system $\mathcal{S} = (\mathbb{S}, \rightarrow)$

Definition

The finite traces semantics $\llbracket \mathcal{S} \rrbracket^*$ is defined by:

$$\llbracket S \rrbracket^{\star} = \{ \langle s_0, \ldots, s_n \rangle \in \mathbb{S}^{\star} \mid \forall i, s_i \to s_{i+1} \}$$

Example:

- contrived transition system $S = (\{a, b, c, d\}, \{(a, b), (b, a), (b, c)\})$
- finite traces semantics:

$$\begin{split} \llbracket \mathcal{S} \rrbracket^{\star} &= \{ \begin{array}{cc} \langle a, b, \dots, a, b, a \rangle, & \langle b, a, \dots, a, b, a \rangle, \\ \langle a, b, \dots, a, b, a, b \rangle, & \langle b, a, \dots, a, b, a, b \rangle, \\ \langle a, b, \dots, a, b, a, b, c \rangle, & \langle b, a, \dots, a, b, a, b, c \rangle \\ \langle c \rangle, & \langle d \rangle & \} \end{split}$$

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Example: imperative program

Similarly, we can write the traces of a simple imperative program:

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- very precise description of what the program does...
- ... but quite cumbersome

Trace semantics fixpoint form

We define a semantic function, that computes the traces of length i + 1 from the traces of length i (where $i \ge 1$):

Finite traces semantics as a fixpoint

Let $\mathcal{I} = \{\epsilon\} \uplus \{\langle s \rangle \mid s \in \mathbb{S}\}.$ Let F_{\star} be the function defined by:

$$\begin{array}{cccc} \mathcal{F}_{\star}: & \mathcal{P}(\mathbb{S}^{\star}) & \longrightarrow & \mathcal{P}(\mathbb{S}^{\star}) \\ & X & \longmapsto & X \cup \{ \langle s_0, \ldots, s_n, s_{n+1} \rangle \mid \langle s_0, \ldots, s_n \rangle \in X \land s_n \to s_{n+1} \} \end{array}$$

Then, F_{\star} is **continuous** and thus has a least-fixpoint greater than \mathcal{I} ; moreover:

If
$$p_{\mathcal{I}} F_{\star} = \llbracket S \rrbracket^{\star} = \bigcup_{n \in \mathbb{N}} F_{\star}^{n}(\mathcal{I})$$



Trace semantics fixpoint form: example

Example, with the same simple transition system $S = (S, \rightarrow)$:

•
$$\mathbb{S} = \{a, b, c, d\}$$

$$ullet o$$
 is defined by $a o b$, $b o a$ and $b o c$

Then, the first iterates are:

$$\begin{array}{lll} F^0_{\star}(\mathcal{I}) &=& \{\epsilon, \langle a \rangle, \langle b \rangle, \langle c \rangle, \langle d \rangle \} \\ F^1_{\star}(\mathcal{I}) &=& F^0_{\star}(\mathcal{I}) \cup \{ \langle b, a \rangle, \langle a, b \rangle, \langle b, c \rangle \} \\ F^2_{\star}(\mathcal{I}) &=& F^1_{\star}(\mathcal{I}) \cup \{ \langle a, b, a \rangle, \langle b, a, b \rangle, \langle a, b, c \rangle \} \\ F^3_{\star}(\mathcal{I}) &=& F^2_{\star}(\mathcal{I}) \cup \{ \langle b, a, b, a \rangle, \langle a, b, a, b \rangle, \langle b, a, b, c \rangle \} \\ F^4_{\star}(\mathcal{I}) &=& F^3_{\star}(\mathcal{I}) \cup \{ \langle a, b, a, b, a \rangle, \langle b, a, b, a, b \rangle, \langle a, b, a, b, c \rangle \} \\ F^5_{\star}(\mathcal{I}) &=& \dots \end{array}$$

• the traces of $[S]^*$ of length n+1 appear in $F^n_*(\mathcal{I})$

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Agenda			
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Operational semantics

- Transition systems and small step semantics
- Traces semantics
 - Definitions
 - Finite traces semantics
 - Fixpoint definition

Summary





Summary

We have discussed:

- small-step / structural operational semantics: individual program steps
- big-step / natural semantics: program executions as sequences of transitions
- their fixpoint definitions and properties

Next:

- another family of semantics, more compact and compositional
- semantic program and proof methods





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Denotational semantics

- Deterministic imperative programs
- Link between operational and denotational semantics
- Instance I an alcusta income formable.

Introduction Operational semantics

Defined as small execution steps (*transition relation*) over low-level internal configurations (*states*)

Transitions are chained to define (*maximal*) traces possibly abstracted as input-output relations (*big-step*)

Denotational semantics

Direct functions from programs to mathematical objects (*denotations*) by induction on the program syntax (*compositional*) ignoring intermediate steps and execution details (*no state*)

⇒ Higher-level, more abstract, more modular. Tries to decouple a program meaning from its execution. Focus on the mathematical structures that represent programs. (founded by Strachey and Scott in the 70s: [Scott-Strachey71])

"Assembly" of semantics vs. "Functional programming" of semantics

Denotation worlds

imperative programs

effect of a program: mutate a memory state natural denotation: input/output function $\mathcal{D} \simeq memory \rightarrow memory$

challenge: build a whole program denotation from denotations of atomic language constructs (modularity)

⇒ very rich theory of mathematical structures (Scott domains, cartesian closed categories, coherent spaces, event structures, game semantics, etc. We will not present them in this overview!)





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Denotational semantics

- Deterministic imperative programs
- Link between operational and denotational semantics
- a lateral englishing and found for
A simple imperative language: IMP

IMP expressions					
expr	::=	X	(variable)		
		С	(constant)		
		$\diamond expr$	(unary operation)		
		$expr \diamond expr$	(binary operation)		

- variables in a fixed set $X \in \mathcal{V}$
- constants $\mathcal{I} \stackrel{\text{def}}{=} \mathbb{B} \cup \mathbb{Z}$:
 - booleans $\mathbb{B} \stackrel{\text{def}}{=} \{ \text{true}, \text{false} \}$
 - $\bullet \ \ \text{integers} \ \mathbb{Z}$
- operations \diamond :
 - integer operations: +, -, ×, /, <, \leq
 - boolean operations: \neg , \wedge , \vee
 - polymorphic operations: =, \neq

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A simple imperative language: IMP

Statements					
stat	::=	skip	(do nothing)		
		$X \leftarrow expr$	(assignment)		
	Í	stat; stat	(sequence)		
		if expr then stat else stat	(conditional)		
		while expr do stat	(loop)		

(inspired from the presentation in [Benton96])



Expression semantics

 $\mathbb{E}[\![\textit{expr}\,]\!]:\mathcal{E} \rightharpoonup \mathcal{I}$

- environments $\mathcal{E} \stackrel{\mathrm{def}}{=} \mathcal{V} \to \mathcal{I}$ map variables in \mathcal{V} to values in \mathcal{I}
- $\mathbb{E}[\![expr]\!]$ returns a value in \mathcal{I}
- → denotes partial functions (as opposed to →) necessary because some operations are undefined
 - $1 + \mathsf{true}, \ 1 \wedge 2$
 - 3/0

(type mismatch) (invalid value)

defined by structural induction on abstract syntax trees (next slide)

(when we use the notation $\mathbb{X}[\![y]\!]$, y is a syntactic object; X serves to distinguish between different semantic functions with different signatures, often varying with the kind of syntactic object y (expression, statement, etc.); $\mathbb{X}[\![y]\!]z$ is the application of the function $\mathbb{X}[\![y]\!]$ to the object z)



Expression semantics

$$\mathbb{E}\llbracket c \ \|\rho \qquad \stackrel{\text{def}}{=} c \qquad \in \mathcal{I}$$

$$\mathbb{E}\llbracket V \ \|\rho \qquad \stackrel{\text{def}}{=} \rho(V) \qquad \in \mathcal{I}$$

$$\mathbb{E}\llbracket V \ \|\rho \qquad \stackrel{\text{def}}{=} -v \qquad \in \mathbb{Z} \quad \text{if } v = \mathbb{E}\llbracket e \ \|\rho \in \mathbb{Z}$$

$$\mathbb{E}\llbracket -e \ \|\rho \qquad \stackrel{\text{def}}{=} -v \qquad \in \mathbb{Z} \quad \text{if } v = \mathbb{E}\llbracket e \ \|\rho \in \mathbb{Z}$$

$$\mathbb{E}\llbracket -e \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 + v_2 \qquad \in \mathbb{Z} \quad \text{if } v_1 = \mathbb{E}\llbracket e \ \|\rho \in \mathbb{Z}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z}$$

$$\mathbb{E}\llbracket e_1 + e_2 \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 + v_2 \qquad \in \mathbb{Z} \quad \text{if } v_1 = \mathbb{E}\llbracket e_1 \ \|\rho \in \mathbb{Z}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z}$$

$$\mathbb{E}\llbracket e_1 - e_2 \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 + v_2 \qquad \in \mathbb{Z} \quad \text{if } v_1 = \mathbb{E}\llbracket e_1 \ \|\rho \in \mathbb{Z}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z}$$

$$\mathbb{E}\llbracket e_1 \wedge e_2 \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 \wedge v_2 \qquad \in \mathbb{Z} \quad \text{if } v_1 = \mathbb{E}\llbracket e_1 \ \|\rho \in \mathbb{Z}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z} \setminus \mathbb{Z} \setminus \{0\}$$

$$\mathbb{E}\llbracket e_1 \wedge e_2 \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 \wedge v_2 \qquad \in \mathbb{B} \quad \text{if } v_1 = \mathbb{E}\llbracket e_1 \ \|\rho \in \mathbb{B}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z} \setminus \{0\}$$

$$\mathbb{E}\llbracket e_1 \vee e_2 \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 \wedge v_2 \qquad \in \mathbb{B} \quad \text{if } v_1 = \mathbb{E}\llbracket e_1 \ \|\rho \in \mathbb{B}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z} \setminus \{0\}$$

$$\mathbb{E}\llbracket e_1 \vee e_2 \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 \vee v_2 \qquad \in \mathbb{B} \quad \text{if } v_1 = \mathbb{E}\llbracket e_1 \ \|\rho \in \mathbb{Z}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z} \setminus \{0\}$$

$$\mathbb{E}\llbracket e_1 \vee e_2 \ \|\rho \qquad \stackrel{\text{def}}{=} v_1 \vee v_2 \ \in \mathbb{B} \quad \text{if } v_1 = \mathbb{E}\llbracket e_1 \ \|\rho \in \mathbb{Z}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z} \setminus \{0\} \in \mathbb{Z} \mid e_1 \ \|\rho \in \mathbb{Z}, v_2 = \mathbb{E}\llbracket e_2 \ \|\rho \in \mathbb{Z} \mid e_2$$

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undefined otherwise

Statement semantics

 $\mathbb{S}[\![\mathsf{stat}]\!]:\mathcal{E} \rightharpoonup \mathcal{E}$

- maps an environment before the statement to an environment after the statement
- partial function due to
 - errors in expressions
 - non-termination
- also defined by structural induction



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Summary

Rewriting the semantics using total functions on cpos:

• $\mathbb{E}[\![expr]\!]: \mathcal{E}_{\perp} \xrightarrow{c} \mathcal{I}_{\perp}$ returns \perp for an error or if its argument is \perp • $\mathbb{S}[\mathsf{stat}]: \mathcal{E}_{\perp} \xrightarrow{c} \mathcal{E}_{\perp}$ • $\mathbb{S}[\![\mathbf{skip}]\!] \rho \stackrel{\mathrm{def}}{=} \rho$ • $\mathbb{S}\llbracket e_1; e_2 \rrbracket \stackrel{\text{def}}{=} \mathbb{S}\llbracket e_2 \rrbracket \circ \mathbb{S}\llbracket e_1 \rrbracket$ • $\mathbb{S}[X \leftarrow e] \rho \stackrel{\text{def}}{=} \begin{cases} \bot & \text{if } \mathbb{E}[e] \rho = \bot \\ \rho[X \mapsto \mathbb{E}[e] \rho] & \text{otherwise} \end{cases}$ • $\mathbb{S}[[if e \text{ then } s_1 \text{ else } s_2]] \rho \stackrel{\text{def}}{=} \begin{cases} \mathbb{S}[[s_1]] \rho & \text{if } \mathbb{E}[[e]] \rho = \text{true} \\ \mathbb{S}[[s_2]] \rho & \text{if } \mathbb{E}[[e]] \rho = \text{false} \\ \downarrow & \text{otherwise} \end{cases}$ • S while e do s = Ifp Fwhere $F(f)(\rho) = \begin{cases} \rho & \text{if } \mathbb{E}\llbracket e \rrbracket \rho = \text{false} \\ f(\mathbb{S}\llbracket s \rrbracket \rho) & \text{if } \mathbb{E}\llbracket e \rrbracket \rho = \text{true} \\ \bot & \text{otherwise} \end{cases}$

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Statement semantics: loops

How do we handle loops?

the semantics of loops must satisfy:

```
\begin{split} \mathbb{S}[\![ \textbf{while } e \textbf{ do } s ]\!]\rho &= \\ \left\{ \begin{array}{ll} \rho & \text{if } \mathbb{E}[\![ e ]\!]\rho = \text{false} \\ \mathbb{S}[\![ \textbf{while } e \textbf{ do } s ]\!](\mathbb{S}[\![ s ]\!]\rho) & \text{if } \mathbb{E}[\![ e ]\!]\rho = \text{true} \\ \text{undefined} & \text{otherwise} \end{array} \right. \end{split}
```

this is a recursive definition, we must prove that:

- the equation has solutions
- o choose the right one
- \implies we use fixpoints on partially ordered sets

Avionics Software Security properties Static analysis Denotationa Operational semantics B. B. B B B D. D. 0

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Denotational semantics

- Deterministic imperative programs
- Link between operational and denotational semantics
- Interval analysis in the famous flow

Motivation

Are the operational and denotational semantics consistent with each other?

Note that:

- systems are actually described operationally
- the denotational semantics is a more abstract representation (more suitable for some reasoning on the system)

 \Longrightarrow the denotational semantics must be proven faithful (in some sense) to the operational model to be of any use



Reminder: from traces to big-step semantics

Big-step semantics: abstraction of traces only remembers the input-output relations

many variants exist:

- "angelic" semantics, in $\mathcal{P}(\Sigma \times \Sigma)$: $\mathbb{A}[\![s]\!] \stackrel{\text{def}}{=} \{(\sigma, \sigma') \mid \exists (\sigma_0, \dots, \sigma_n) \in t[\![s]\!]^*: \sigma = \sigma_0, \sigma' = \sigma_n \}$ (only give information on the terminating behaviors; can only prove partial correctness)
- natural semantics, in $\mathcal{P}(\Sigma \times \Sigma_{\perp})$: $\mathbb{N}[\![s]\!] \stackrel{\text{def}}{=} \mathbb{A}[\![s]\!] \cup \{(\sigma, \perp) \mid \exists (\sigma_0, \ldots) \in t[\![s]\!]^{\omega}: \sigma = \sigma_0 \}$ (models the terminating and non-terminating behaviors;

can prove total correctness)





Operational semantics 20.

Denotationa

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(5) Denotational semantics

- Deterministic imperative programs
- Link between operational and denotational semantics

Language

Expressions and conditions					
expr	::=	V	$V\in \mathcal{V}$		
		С	$c\in\mathbb{Z}$		
		-expr			
		$expr \diamond expr$	$\diamond \in \{+,-,\times,/\}$		
		rand(a,b)	${\sf a},{\sf b}\in\mathbb{Z}$		
cond	::=	expr ⋈ expr ⊐cond	$\bowtie \in \{\leq,\geq,=,\neq,<,>\}$		
		cond <> cond	$\diamond \in \{\land,\lor\}$		

C .			
- C +	- http://www.com/com/to/	$\sim m$	onte
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stat ::= V ← expr
| if cond then stat else stat
| while cond do stat
| stat; stat
| skip



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Concrete semantics

Classic non-deterministic concrete semantics, in denotational style:

 $\mathbb{E}\llbracket expr \rrbracket : \mathcal{E} \to \mathcal{P}(\mathbb{Z}) \qquad (arithmetic expressions)$ $\mathbb{E}[\![V]\!]\rho \qquad \stackrel{\text{def}}{=} \{\rho(V)\}$ $\mathbb{E}[\![c]\!]\rho \qquad \stackrel{\text{def}}{=} \{c\}$ $\mathbb{E}[\operatorname{rand}(a, b)] \rho \stackrel{\text{def}}{=} \{ x \mid a < x < b \}$ $\mathbb{E}\llbracket -e \rrbracket \rho \qquad \qquad \stackrel{\text{def}}{=} \{ -v \mid v \in \mathbb{E}\llbracket e \rrbracket \rho \}$ $\mathbb{E}[\![e_1 \diamond e_2]\!]\rho \qquad \stackrel{\text{def}}{=} \{v_1 \diamond v_2 \mid v_1 \in \mathbb{E}[\![e_1]\!]\rho, v_2 \in \mathbb{E}[\![e_2]\!]\rho, \diamond \neq / \lor v_2 \neq 0\}$ $\mathbb{C}[\text{cond}]: \mathcal{E} \to \mathcal{P}(\{\text{true}, \text{false}\})$ (boolean conditions) $\mathbb{C}\llbracket \neg c \rrbracket \rho \qquad \stackrel{\text{def}}{=} \{ \neg v \mid v \in \mathbb{C}\llbracket c \rrbracket \rho \}$ $\mathbb{C}\llbracket c_1 \diamond c_2 \llbracket \rho \quad \stackrel{\text{def}}{=} \{ v_1 \diamond v_2 \mid v_1 \in \mathbb{C}\llbracket c_1 \rrbracket \rho, v_2 \in \mathbb{C}\llbracket c_2 \rrbracket \rho \}$ $\mathbb{C}[e_1 \boxtimes e_2] \rho \stackrel{\text{def}}{=} \{ \text{true} \mid \exists v_1 \in \mathbb{E}[e_1] \rho, v_2 \in \mathbb{E}[e_2] \rho; v_1 \boxtimes v_2 \} \cup$ { false $| \exists v_1 \in \mathbb{E} \llbracket e_1 \rrbracket \rho, v_2 \in \mathbb{E} \llbracket e_2 \rrbracket \rho; v_1 \not\bowtie v_2$ } where $\mathcal{E} \stackrel{\text{def}}{=} \mathcal{V} \to \mathbb{Z}$

Concrete semantics

$\underline{\mathbb{S}[\![\mathit{stat}\,]\!]}:\mathcal{P}(\mathcal{E})\to\mathcal{P}(\mathcal{E})$

$$\begin{split} & \mathbb{S}[\![\mathbf{skip}]\!]R & \stackrel{\text{def}}{=} R \\ & \mathbb{S}[\![\mathbf{s}_1; \mathbf{s}_2]\!]R & \stackrel{\text{def}}{=} \mathbb{S}[\![\mathbf{s}_2]\!](\mathbb{S}[\![\mathbf{s}_1]\!]R) \\ & \mathbb{S}[\![V \leftarrow e]\!]R & \stackrel{\text{def}}{=} \{\rho[V \mapsto v] \mid \rho \in R, v \in \mathbb{E}[\![e]\!]\rho \} \\ & \mathbb{S}[\![\mathbf{if} \ c \ \mathbf{then} \ \mathbf{s}_1 \ \mathbf{else} \ \mathbf{s}_2]\!]R & \stackrel{\text{def}}{=} \mathbb{S}[\![\mathbf{s}_1]\!](\mathbb{S}[\![c?]\!]R) \cup \mathbb{S}[\![\mathbf{s}_2]\!](\mathbb{S}[\![\neg c?]\!]R) \\ & \mathbb{S}[\![\mathbf{while} \ c \ \mathbf{do} \ \mathbf{s}]\!]R & \stackrel{\text{def}}{=} \mathbb{S}[\![\neg c?]\!](\mathrm{lfp} \ \lambda I. \ R \cup \mathbb{S}[\![\mathbf{s}]\!](\mathbb{S}[\![c?]\!]I)) \\ & \text{where} \\ & \mathbb{S}[\![c?]\!]R & \stackrel{\text{def}}{=} \{\rho \in R \mid \mathrm{true} \in \mathbb{C}[\![c]\!]\rho \} \end{split}$$

 $\mathbb{S}[[stat]]$ is a \cup -morphism in the complete lattice $(\mathcal{P}(\mathcal{E}), \subseteq, \cup, \cap, \emptyset, \mathcal{E})$

Reminder: Non-relational abstractions

<u>Reminder:</u> we compose two abstractions:

- $\mathcal{P}(\mathcal{V} \to \mathbb{Z})$ is abstracted as $\mathcal{V} \to \mathcal{P}(\mathbb{Z})$
- $\mathcal{P}(\mathbb{Z})$ is abstracted as intervals $\mathcal I$

(forget relationship) (keep only bounds)



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Interval expression evaluation

 $\mathbb{E}^{\sharp}\llbracket expr \rrbracket : \mathcal{E}^{\sharp} \to \mathcal{I}$ interval version of $\mathbb{E}\llbracket expr \rrbracket : \mathcal{E} \to \mathcal{P}(\mathbb{Z})$

Definition by structural induction, very similar to $\mathbb{E}[\![expr]\!]$

$$\begin{split} \mathbb{E}^{\sharp} \llbracket V \rrbracket X^{\sharp} & \stackrel{\text{def}}{=} X^{\sharp}(V) \\ \mathbb{E}^{\sharp} \llbracket c \rrbracket X^{\sharp} & \stackrel{\text{def}}{=} [c, c] \\ \mathbb{E}^{\sharp} \llbracket \operatorname{rand}(a, b) \rrbracket X^{\sharp} & \stackrel{\text{def}}{=} [a, b] \\ \mathbb{E}^{\sharp} \llbracket -e \rrbracket X^{\sharp} & \stackrel{\text{def}}{=} -^{\sharp} \mathbb{E}^{\sharp} \llbracket e \rrbracket X^{\sharp} \\ \mathbb{E}^{\sharp} \llbracket e_{1} \diamond e_{2} \rrbracket X^{\sharp} & \stackrel{\text{def}}{=} \mathbb{E}^{\sharp} \llbracket e_{1} \rrbracket X^{\sharp} \diamond^{\sharp} \mathbb{E}^{\sharp} \llbracket e_{2} \rrbracket X^{\sharp} \end{split}$$

Interval arithmetic

•
$$-^{\sharp}[a,b] = [-b,-a]$$

•
$$[a, b] +^{\sharp} [c, d] = [a + c, b + d]$$

•
$$[a, b] -^{\sharp} [c, d] = [a - d, b - c]$$

•
$$\forall i \in \mathcal{I}: -^{\sharp} \perp = \perp +^{\sharp} i = i +^{\sharp} \perp = \cdots = \perp$$
 (strictness)

where:
$$+$$
 and $-$ is extended to $+\infty$, $-\infty$ as:
 $\forall x \in \mathbb{Z}: (+\infty) + x = +\infty, (-\infty) + x = -\infty, -(+\infty) = (-\infty), \dots$

•
$$[a, b] \times^{\sharp} [c, d] = [\min(a \times c, a \times d, b \times c, b \times d), \max(a \times c, a \times d, b \times c, b \times d)]$$

where \times is extended to $+\infty$ and $-\infty$ by the rule of signs: $c \times (+\infty) = (+\infty)$ if c > 0, $(-\infty)$ if c < 0 $c \times (-\infty) = (-\infty)$ if c > 0, $(+\infty)$ if c < 0

we also need the non-standard rule: $0\times (+\infty)=0\times (-\infty)=0$

Summary of the abstract semantics

 $\mathbb{S}^{\sharp} \llbracket \operatorname{skip} \rrbracket X^{\sharp} \stackrel{\operatorname{def}}{=} X^{\sharp}$

 $S^{\sharp}[[s_{1}; s_{2}]]X^{\sharp} \stackrel{\text{def}}{=} S^{\sharp}[[s_{2}]](S^{\sharp}[[s_{1}]]X^{\sharp})$ $S^{\sharp}[[V \leftarrow e]]X^{\sharp} \stackrel{\text{def}}{=} \begin{cases} X^{\sharp}[V \mapsto \mathbb{E}^{\sharp}[[e]]X^{\sharp}] & \text{if } \mathbb{E}^{\sharp}[[e]]X^{\sharp} \neq \bot \\ \bot & \text{if } \mathbb{E}^{\sharp}[[e]]X^{\sharp} = \bot \end{cases}$ $S^{\sharp}[[if c \text{ then } s_{1} \text{ else } s_{2}]]X^{\sharp} \stackrel{\text{def}}{=} S^{\sharp}[[s_{1}]](S^{\sharp}[[c?]]X^{\sharp}) \stackrel{\cup^{\sharp}}{=} S^{\sharp}[[s_{2}]](S^{\sharp}[[\neg c?]]X^{\sharp})$ $S^{\sharp}[[while c \text{ do } s]]X^{\sharp} \stackrel{\text{def}}{=} S^{\sharp}[[\neg c?]](\lim \lambda I^{\sharp}.I^{\sharp} \stackrel{\bigtriangledown}{=} (X^{\sharp} \cup^{\sharp} S^{\sharp}[[s]](S^{\sharp}[[c?]]I^{\sharp})))$

(next slides: extending the language with assertions and local variables)

Convergence acceleration

Widening: binary operator
$$\nabla : \mathcal{E}^{\sharp} \times \mathcal{E}^{\sharp} \to \mathcal{E}^{\sharp}$$
 such that:

•
$$\gamma(X^{\sharp})\cup\gamma(Y^{\sharp})\subseteq\gamma(X^{\sharp} \triangledown Y^{\sharp})$$

(sound abstraction of \cup)

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• for any sequence $(X_n^{\sharp})_{n \in \mathbb{N}}$, the sequence $(Y_n^{\sharp})_{n \in \mathbb{N}}$

$$\begin{cases} Y_0^{\sharp} \stackrel{\text{def}}{=} X_0^{\sharp} \\ Y_{n+1}^{\sharp} \stackrel{\text{def}}{=} Y_n^{\sharp} \bigtriangledown X_{n+1}^{\sharp} \end{cases}$$

stabilizes in finite time: $\exists N \in \mathbb{N} \colon Y_N^{\sharp} = Y_{N+1}^{\sharp}$

Fixpoint approximation theorem:

• the sequence $X_{n+1}^{\sharp} \stackrel{\text{def}}{=} X_n^{\sharp} \bigtriangledown F^{\sharp}(X_n^{\sharp})$ stabilizes in finite time

• when
$$X_{N+1}^{\sharp} \sqsubseteq X_{N}^{\sharp}$$
, then X_{N}^{\sharp} abstracts lfp *F*

 $\begin{array}{l} \underline{\text{Soundness proof:}} \quad \text{assume } X_{N+1}^{\sharp} \sqsubseteq X_{N}^{\sharp}, \text{ then} \\ \hline \gamma(X_{N}^{\sharp}) \supseteq \gamma(X_{N+1}^{\sharp}) = \gamma(X_{N}^{\sharp} \triangledown F^{\sharp}(X_{N}^{\sharp})) \supseteq \gamma(F^{\sharp}(X_{N}^{\sharp})) \supseteq F(\gamma(X_{N}^{\sharp})) \\ \gamma(X_{N}^{\sharp}) \text{ is a post-fixpoint of } F, \text{ but Ifp } F \text{ is } F \text{'s least post-fixpoint, so, } \gamma(X_{N}^{\sharp}) \supseteq \text{ Ifp } F \end{array}$

Interval widening

Interval widening $\nabla : \mathcal{I} \times \mathcal{I} \to \mathcal{I}$

$$\forall l \in \mathcal{I} \colon \bot \bigtriangledown l = l \lor \bot = l \\ [a, b] \lor [c, d] \stackrel{\text{def}}{=} \left[\begin{cases} a & \text{if } a \leq c \\ -\infty & \text{if } a > c \end{cases}, \begin{cases} b & \text{if } b \geq d \\ +\infty & \text{if } b < d \end{cases} \right]$$

- ${\, \bullet \,}$ an unstable lower bound is put to $-\infty$
- ${\, \bullet \,}$ an unstable upper bound is put to $+\infty$
- ${\, \bullet \,}$ once at $-\infty$ or $+\infty,$ the bound becomes stable

 $\underline{\text{Point-wise lifting:}} \quad \dot{\nabla} : \mathcal{E}^{\sharp} \times \mathcal{E}^{\sharp} \to \mathcal{E}^{\sharp}$

$$X^{\sharp} \stackrel{\mathrm{\dot{\bigtriangledown}}}{ o} Y^{\sharp} \stackrel{\mathrm{def}}{=} \lambda V \in \mathcal{V}. X^{\sharp}(V) \triangledown Y^{\sharp}(V)$$

extrapolate each variable independently

 \implies stabilization in at most $2|\mathcal{V}|$ iterations

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